

Math 235 HW # 11

Section 5.1 # 3, 19, 23abc, 24, 26

5.1 #3

$$A = \begin{bmatrix} -1 & -2 \\ 4 & 5 \end{bmatrix}$$

$$\begin{aligned} |\lambda I - A| &= \begin{vmatrix} \lambda+1 & 2 \\ -4 & \lambda-5 \end{vmatrix} = (\lambda+1)(\lambda-5) + 8 \\ &= \lambda^2 - 4\lambda - 5 + 8 = \lambda^2 - 4\lambda + 3 \\ &= (\lambda-3)(\lambda-1) \end{aligned}$$

$$\lambda = 3, 1$$

$\lambda=3$

$$\begin{bmatrix} 4 & 2 & | & 0 \\ -4 & -2 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1/2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\begin{aligned} y &= r \\ x + \frac{1}{2}r &= 0 \\ x &= -\frac{1}{2}r \end{aligned}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -\frac{1}{2}r \\ r \end{bmatrix} = r \begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$$

$\begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$ is an eigenvector with eigenvalue 3.

$\lambda=1$

$$\begin{bmatrix} 2 & 2 & | & 0 \\ -4 & -4 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\begin{aligned} y &= r \\ x &= -r \end{aligned}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -r \\ r \end{bmatrix} = r \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$ is an eigenvector with eigenvalue 1.

5.1 #19

$$T((x_1, x_2, x_3)) = [x_1 + x_3, x_2, x_1 + x_3]$$

matrix: $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

$$|\lambda I - A| = \begin{vmatrix} \lambda-1 & 0 & -1 \\ 0 & \lambda-1 & 0 \\ -1 & 0 & \lambda-1 \end{vmatrix} = (\lambda-1) \begin{vmatrix} \lambda-1 & -1 \\ -1 & \lambda-1 \end{vmatrix}$$

$$= (\lambda-1)((\lambda-1)^2 - 1) = (\lambda-1)(\lambda^2 - 2\lambda + 1 - 1)$$

$$= (\lambda-1)(\lambda-2)\lambda \quad \lambda = 0, 1, 2$$

$\lambda=0$

$$\begin{bmatrix} -1 & 0 & -1 & | & 0 \\ 0 & -1 & 0 & | & 0 \\ -1 & 0 & -1 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\begin{aligned} z &= r \\ y &= 0 \\ x &= -r \end{aligned}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -r \\ 0 \\ r \end{bmatrix} = r \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$[-1, 0, 1]$ is an eigenvector with eigenvalue 0.

$\lambda=1$

$$\begin{bmatrix} 0 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ -1 & 0 & 0 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\begin{aligned} z &= 0 \\ y &= r \\ x &= 0 \end{aligned}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ r \\ 0 \end{bmatrix} = r \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$[0, 1, 0]$ is an eigvec with eigenvalue 1.

S.1 #19 c+d

$\lambda=2$

$$\left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad \begin{array}{l} z=r \\ y=0 \\ x=r \end{array} \quad \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} r \\ 0 \\ r \end{bmatrix} = r \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$[1, 0, 1]$ is an eigvec with eigenval 2.

S.1 #23a

False - when you solve the char. polyn, the solutions might not be real. e.g. $\lambda^2+1=0 \rightarrow \lambda=\pm i$

23b

False - the roots of the char polyn might not be distinct. e.g. $(\lambda-1)^2=0 \rightarrow \lambda=1,1$

23c

True - the roots of the char polyn may be complex, and might not be distinct.

S.1 #24

Let T be linear, $\lambda \in \mathbb{R}$, $S = \{ \vec{v} \mid T(\vec{v}) = \lambda \vec{v} \}$. Show S is a subspace.

PF

closed under + Take $\vec{u}, \vec{v} \in S$, so $T(\vec{u}) = \lambda \vec{u}$ and $T(\vec{v}) = \lambda \vec{v}$.
Will show $\vec{u} + \vec{v} \in S$, i.e. $T(\vec{u} + \vec{v}) = \lambda(\vec{u} + \vec{v})$.

$$\begin{aligned} \text{Here goes: } T(\vec{u} + \vec{v}) &= T(\vec{u}) + T(\vec{v}) && (T \text{ is linear}) \\ &= \lambda \vec{u} + \lambda \vec{v} = \lambda(\vec{u} + \vec{v}) && \checkmark \end{aligned}$$

closed under mult Take $\vec{u} \in S$, $k \in \mathbb{R}$. So $T(\vec{u}) = \lambda \vec{u}$,
will show $k\vec{u} \in S$, i.e. $T(k\vec{u}) = \lambda k\vec{u}$.

$$\begin{aligned} \text{We have: } T(k\vec{u}) &= kT(\vec{u}) && (T \text{ is linear}) \\ &= k\lambda \vec{u} = \lambda k\vec{u} && \checkmark \end{aligned}$$

S.1 #26

$T(f) = f^{(4)}$ fourth deriv.

$$T(e^{ax}) = a^4 e^{ax}$$

so e^{ax} is an eigvec with eigenval a^4

$$\begin{aligned} T(e^{-ax}) &= (-a)^4 e^{-ax} \\ &= a^4 e^{-ax} \end{aligned}$$

so e^{-ax} is an eigvec with eigenval a^4

$$T(\sin ax) = a^4 \sin ax$$

so $\sin ax$ is an eigvec with eigenval a^4

$$T(\cos ax) = a^4 \cos ax$$

so $\cos ax$ is an eigvec with eigenval a^4