

Math 235 HW #7

Section 2.3 #9, 14, 18, 31

Section 2.4 #4

2.3 #9

$$T([-1, 2]) = [1, 0, 0]$$

$$T([2, 1]) = [0, 1, 2].$$

Let's find $T([0, 10])$. First write $[0, 10] = c_1[-1, 2] + c_2[2, 1]$

$$\begin{array}{l} -c_1 + 2c_2 = 0 \\ 2c_1 + c_2 = 10 \end{array} \quad \left[\begin{array}{cc|c} -1 & 2 & 0 \\ 2 & 1 & 10 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 0 & 4 \\ 0 & 1 & 2 \end{array} \right] \quad \begin{array}{l} c_1 = 4 \\ c_2 = 2 \end{array}$$

$$T([0, 10]) = T(4[-1, 2] + 2[2, 1])$$

$$= 4T([-1, 2]) + 2T([2, 1])$$

$$= 4[1, 0, 0] + 2[0, 1, 2]$$

$$= [4, 2, 4]$$

2.3 #14

$$T([x_1, x_2]) = [2x_1, -x_2, x_1 + x_2, x_1 + 3x_2]$$

$$T([1, 0]) = [2, 1, 1]$$

$$T([0, 1]) = [-1, 1, 3]$$

the matrix is $\begin{bmatrix} 2 & -1 \\ 1 & 1 \\ 1 & 3 \end{bmatrix}$

2.3 #18

$$T([x_1, x_2, x_3]) = x_1 + x_2 + x_3$$

$$T([1, 0, 0]) = 1$$

$$T([0, 1, 0]) = 1 \quad \text{matrix is } \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$$

$$T([0, 0, 1]) = 1$$

2.3 #3) If T and T' are linear, show $T' \circ T^*$ is linear.

Preserves +

We need to show $T' \circ T^*(\vec{u} + \vec{v}) = T' \circ T^*(\vec{u}) + T' \circ T^*(\vec{v})$

$$\begin{aligned} T' \circ T^*(\vec{u} + \vec{v}) &= T(T^*(\vec{u} + \vec{v})) = T(T^*(\vec{u}) + T^*(\vec{v})) \quad \text{since } T^* \text{ is linear} \\ &= T(T(\vec{u})) + T(T(\vec{v})) \quad \text{since } T \text{ is linear} \\ &= T' \circ T(\vec{u}) + T' \circ T(\vec{v}) \quad \text{as desired.} \end{aligned}$$

Preserves sum

We need $T' \circ T(r\vec{u}) = r T' \circ T(\vec{u})$

$$\begin{aligned} T' \circ T(r\vec{u}) &= T'(T(r\vec{u})) = T'(rT(\vec{u})) \quad \text{since } T \text{ is linear} \\ &= r T'(T(\vec{u})) \quad \text{since } T' \text{ is linear} \end{aligned}$$

2.4 #4 formulas for $\sin 3\theta$, $\cos 3\theta$.

rotation by 3θ is

$$\begin{bmatrix} \cos 3\theta & -\sin 3\theta \\ \sin 3\theta & \cos 3\theta \end{bmatrix}$$

this equals 3 rotations by θ :

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos^3 \theta - \sin^2 \theta \cos \theta & -2 \sin \theta \cos^2 \theta \\ 2 \sin \theta \cos \theta & \cos^3 \theta + \sin^2 \theta \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos^3 \theta - \cos \theta \sin^2 \theta - 2 \sin^2 \theta \cos \theta \\ 2 \sin \theta \cos^2 \theta + \cos^2 \theta \sin^2 \theta \end{bmatrix} \sim \begin{bmatrix} \cos 3\theta \\ \sin 3\theta \end{bmatrix}$$

$$\therefore \cos 3\theta = \cos^3 \theta - \cos \theta \sin^2 \theta - 2 \sin^2 \theta \cos \theta$$

$$\sin 3\theta = 2 \sin \theta \cos^2 \theta + \cos^2 \theta \sin^2 \theta$$